

# PATENT ABSTRACTS OF JAPAN

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(54) POSITION DETECTION METHOD FOR OPTICAL DISPLACEMENT  
METER AND OPTICAL DISPLACEMENT METER USING THIS METHOD

(57)Abstract:

PURPOSE: To detect displacement accurately and stably with an optical displacement meter without using a multitude of comparators or accurate comparators.

CONSTITUTION: Each of a pair of position signals output from a position detection element 105 is amplified with an amplifier selected among a plurality of amplification factors set up in advance. Each amplification factor is simultaneously increased or decreased in turn so that the sum signal of the pair of amplified signals is in the window level specified by the determined maximum level EH and the minimum level EL capable of processing the signal.

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CLAIMS

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[Claim(s)]

[Claim 1] It is a position detection method used for an optical displacement meter which receives light by a position detecting element which outputs modulated light towards an object from a light emitting device and outputs a position signal of a couple [ catoptric light / by an object ] according to a light-receiving position and measured the objective amount of displacement. Each of a position signal of a couple outputted from the above-mentioned position detecting element is amplified with an amplification factor selected from two or more amplification factors set up beforehand. A position detection method of an optical displacement meter characterized by making it increase or reduce an amplification factor of each above one by one simultaneously so that a summed signal of a position signal of an amplified couple may enter in a window level which becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible.

[Claim 2] An optical displacement meter which receives light by a position detecting element which outputs modulated light towards an object from a light emitting device and outputs a position signal of a couple [ catoptric light / by an object ] according to a light-receiving position and measured the objective amount of displacement comprising:

1 set of variable amplifiers which amplify individually each of a position signal of a couple outputted from the above-mentioned position detecting element with an amplification factor selected from two or more amplification factors set up beforehand.

An adder circuit adding a position signal of a couple amplified in this variable amplifier.

A level discrimination section which distinguishes whether it enters in a window level in which the above-mentioned summed signal becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible.

When the above-mentioned summed signal exceeds the above-mentioned

maximum level according to a discrimination signal which was defined beforehand and which is outputted from the above-mentioned level discrimination section for every given period an amplification factor control section to which an amplification factor of a variable amplifier of each above is made to increase from the present amplification factor by simultaneously by one step when the above-mentioned summed signal falls from the above-mentioned minimum level while reducing an amplification factor of a variable amplifier of each above simultaneously by one step from the present amplification factor.

[Claim 3] It is a position detection method used for an optical displacement meter with the feedback loop of an optical system which receives light by a position detecting element which outputs modulated light towards an object from a light emitting device and outputs a position signal of a couple [ catoptric light / by an object ] according to a light-receiving position and measured the objective amount of displacement. Each of a position signal of a couple outputted from the above-mentioned position detecting element is amplified with an amplification factor selected from two or more amplification factors set up beforehand. An error integration signal which searched for and searched for an error integration signal as compared with predetermined reference level a summed signal of a position signal of an amplified couple so that it may enter in a window level which becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible. A position detection method of an optical displacement meter it was made to increase or reduce an amplification factor of each above one by one simultaneously.

[Claim 4] An optical displacement meter characterized by comprising the following with the feedback loop of an optical system which receives light by a position detecting element which outputs modulated light towards an object from a light emitting device and outputs a position signal of a couple [ catoptric light / from an object ] according to a light-receiving position and measured the objective amount of displacement.

1 set of variable amplifiers which amplify individually each of a position signal of a couple outputted from the above-mentioned position detecting element with an amplification factor selected from two or more amplification factors set up beforehand.

An adder circuit adding a position signal of a couple amplified in this variable amplifier.

An error integration circuit which integrates with a part for the error as compared with reference level which was able to define the above-mentioned summed signal beforehand.

A level discrimination section which distinguishes whether it enters in a window level in which the above-mentioned error integration signal becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible.

When the above-mentioned error integration signal exceeds the above-mentioned maximum level according to a discrimination signal which was defined beforehand and which is outputted from the above-mentioned level discrimination section for every given period an amplification factor control section which reduces an amplification factor of a variable amplifier of each above simultaneously by one step from the present amplification factor when the above-mentioned error integration signal falls from the above-mentioned minimum level while making an amplification factor of a variable amplifier of each above increase from the present amplification factor by one step.

[0001]

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## DETAILED DESCRIPTION

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[Detailed Description of the Invention]

[Industrial Application] This invention relates to the optical displacement meter

using the position detection method with which the optical displacement meter was improved and this method.

[0002]

[Description of the Prior Art] Modulated light is outputted towards an object from a light emitting device and the optical displacement meter which receives the catoptric light by an object by a position detecting element and measured the objective amount of displacement has come to be developed and used. Drawing 10 is what showed the example of an internal configuration of such an optical displacement meter 100 synchronizing with the pulse outputted from the oscillating circuit 101 a modulating signal is transmitted to the laser diode driver 103 from the modulation circuit 102 and a laser beam is outputted to an object from the laser diode 104. Then the position signal I1 of the couple according to the position in which the laser beam reflected by the object entered into the position detecting element 105 and I2 are outputted and this position signal I1 and I2 are amplified in the amplifying circuit 106 107 and the variable amplifier 108 109 and it restores to them in the signal processing part 110 111. Then  $(I1-I2)$  is calculated in the subtractor circuit 112  $(I1+I2)$  is calculated in the adder circuit 113  $(I1-I2)/(I1+I2)$  is called for in the ratio circuit 114 it is transmitted to the output circuit 115 and the objective amount of displacement is measured by this operation.

[0003] By the way in order to stop the breadth of the dynamic range of the demodulation signal transmitted to the subtractor circuit 112 the adder circuit 113 and the ratio circuit 114 in this optical displacement meter 100 and to raise arithmetic precision Add the output signal of the amplifying circuit 106 107 in the adder circuit 116 rectify a summed signal in the rectification circuit 119 and it transmits to the level discrimination section 117 Negative feedback control is performed so that the amplification factor of the variable amplifier 108 109 may be controlled by the amplification factor control section 118 according to the level of a summed signal and a summed signal level may become constant value.

[0004] That is as shown in drawing 10 they are each comparators 117a and 117b

of the level discrimination section 117... It has 117 n of reference voltage of  $E_a$  and  $E_b \dots E_n$  respectively.

As shown in drawing 11 when the summed signal level  $E$  increases So that the amplification factor  $G_a$  and  $E_c < E < E_e$  may make the amplification factor  $G_{bit}$  may become the amplification factor  $G_c$  in  $E_e < E < E_g$  and it may become the amplification factor  $G_d$  at  $E_g < E < E_h$  in  $E_a < E < E_c$  When the summed signal levels  $E$  decrease in number For the amplification factor  $G_d$  and  $E_f > E > E_d$  to make the amplification factor  $G_c$  to become the amplification factor  $G_b$  in  $E_d > E > E_b$  and to become the amplification factor  $G_a$  in  $E_b > E > E_a$  a hysteresis characteristic is given and the amplification factor of the variable amplifier 108/109 is controlled by  $E_h > E > E_f$  by the amplification factor control section 118.

[0005] Therefore as shown in (a) - (c) of drawing 12 it synchronizes with a clock signal (output signal of the oscillating circuit 101) Negative feedback control is performed so that the position signal  $I_1$  and  $I_2$  may be amplified with the amplification factor (refer to drawing 10) which asked for the level range of the summed signal and was defined according to the range for which it asked from the discrimination signal of each comparator of the level discrimination section 117 and a summed signal ( $I_1 + I_2$ ) may always become constant value.

[0006] However in the optical displacement meter 100 of such composition. As the dynamic range of the summed signal outputted from the adder circuit 116 was shown in drawing 11 in order that the wide range of tens of volts may be covered from several millivolts many amplification factors must be set up in the variable amplifier 108/109 -- this sake -- the level discrimination section 117 -- many comparators 117a and 117b ... being required and since the dynamic range is large In the comparator of the lowa circuit design -- high degree of accuracy is required -- was made difficult.

[0007]

[Problem(s) to be Solved by the Invention] By making this invention in light of the above-mentioned circumstances and controlling so that the summed signal of the

position signal of a couple enters in a predetermined window level. It aims at providing the position detection method which can perform highly precise and stabilized displacement detection even if it does not use many comparators or highly precise comparators. An object of this invention proposed simultaneously is to provide the optical displacement meter which used this position detection method.

[0008]

[Means for Solving the Problem] To achieve the above objects, this invention method according to claim 1 proposed. Each of a position signal of a couple outputted from a position detecting element is amplified with an amplification factor selected from two or more amplification factors set up beforehand. He is trying for an amplification factor of each above to be simultaneously increased or reduced one by one by summed signal of a position signal of an amplified couple so that it may enter in a window level which becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible.

[0009] An optical displacement meter of this invention according to claim 2 is what used this invention method according to claim 1. It is set of variable amplifiers which amplify individually each of a position signal of a couple outputted from a position detecting element with an amplification factor selected from two or more amplification factors set up beforehand. An adder circuit adding a position signal of a couple amplified in this variable amplifier. A level discrimination section which distinguishes whether it enters in a window level in which this summed signal becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible. When the above-mentioned summed signal exceeds the above-mentioned maximum level according to a discrimination signal which was defined beforehand and which is outputted from the above-mentioned level discrimination section for every given period, while reducing an amplification factor of a variable amplifier of each above simultaneously by one step from the present amplification factor. When the above-mentioned summed signal falls from the above-mentioned minimum level, it has composition provided

with an amplification factor control section to which an amplification factor of a variable amplifier of each above is made to increase from the present amplification factor by simultaneously by one step.

[0010]In this invention method which this invention method according to claim 3 is a position detection method used for an optical displacement meter with the feedback loop of an optical system and was indicated to claim 1. He is trying to increase or reduce each amplification factor one by one simultaneously so that an error integration signal acquired in a summed signal as compared with predetermined reference level may be entered instead of a summed signal in a window level which becomes settled in a predetermined maximum level and a minimum level in which signal processing is possible.

[0011]Using this invention method according to claim 3 in the displacement gage according to claim 2, an optical displacement meter of this invention according to claim 4 is replaced with a summed signal and is considered as composition which controls an amplification factor by an error integration signal.

[0012]

[Function]In this invention method according to claim 1, control of an amplification factor is performed so that the position signal of the couple outputted from a position detecting element may be amplified and the summed signal of the amplified signal may enter in the window level which becomes settled in a predetermined maximum level and minimum level. For this reason, since the summed signal of the position signal of a couple is always settled in a predetermined window level, the breadth of a dynamic range is stopped and the data-processing accuracy for displacement measurement can be raised.

[0013]The summed signal which the position signal of the couple outputted from the position detecting element was amplified in 1 set of variable amplifiers was added in this invention according to claim 2 in the adder circuit and was acquired. It is distinguished by the level discrimination section whether it goes into the window level which becomes settled in a predetermined maximum level and minimum level and the discrimination signal is outputted and in an amplification



factor control section. When a summed signal exceeds a maximum level with reference to the discrimination signal of a level discrimination section for every given period While reducing the amplification factor of each variable amplifier simultaneously by one step from the present amplification factor when a summed signal falls from a minimum level the amplification factor of each variable amplifier is made to increase from the present amplification factor by simultaneously by one step and it controls by this so that a summed signal always enters in a window level. For this reason in a level discrimination section while what is necessary is just to distinguish a maximum level and a minimum level and being able to reduce the number of comparators a highly precise comparator becomes unnecessary.

[0014] In this invention method according to claim 3 each of the position signal of the couple outputted from a position detecting element is amplified Control of an amplification factor is performed so that it may enter in the window level in which the error integration signal which searched for the error integration signal and searched for the summed signal of the amplified signal as compared with reference level becomes settled in a predetermined maximum level and minimum level. For this reason since the error integration signal of a summed signal is always settled in a predetermined window level as a result a summed signal will always be settled in a predetermined level the breadth of a dynamic range is stopped and the data-processing accuracy for displacement measurement can be raised.

[0015] In this invention according to claim 4 the position signal of the couple outputted from the position detecting element is amplified in 1 set of variable amplifiers and is added in an adder circuit The acquired summed signal is transmitted to an error integration circuit and an error integration signal is searched for It is distinguished whether the error integration signal searched for is contained in the predetermined window level by the level discrimination section and the discrimination signal is outputted and in an amplification factor control section. When an error integration signal exceeds a maximum level with

reference to the discrimination signal of a level discrimination section for every given period. While making the amplification factor of each variable amplifier increase from the present amplification factor by simultaneously by one step when an error integration signal falls from a minimum level. The amplification factor of each variable amplifier is simultaneously reduced by one step from the present amplification factor and it controls by this so that a summed signal always enters in a window level. For this reason in a level discrimination section while what is necessary is just to distinguish a maximum level and a minimum level and being able to reduce the number of comparators a highly precise comparator becomes unnecessary.

[0016]

[Example] Below the example of this invention is described with reference to drawings. Although the operation of (a) - (c) of drawing 1 until it is what had and showed the position detection method of the optical displacement meter of this invention according to claim 1 for the time chart it outputs modulated light towards an object from a light emitting device and it receives the catoptric light by an object by a position detecting element is the same as that of the conventional displacement gauge. In this invention method the position signal of the couple outputted from a position detecting element is respectively amplified with the amplification factor selected from two or more amplification factors set up discretely beforehand. In [ search for the summed signal of the position signal of the amplified couple and ] the input timing of a clock signal. If this summed signal is over the predetermined maximum level E, H will reduce each amplification factor of the position signal of a couple by one step from the present amplification factor and conversely if the summed signal is falling from predetermined minimum level L, N negative feedback control is performed so that each amplification factor of the position signal of a couple may be made to increase from the present amplification factor by one step. For this reason since it is controlled to enter in the window level in which the aggregate value of the position signal of a couple always becomes settled in a maximum level and a minimum level it can suppress

that the dynamic range of an aggregate value spreads and the arithmetic precision for the amount calculation of displacement can be raised.

[0017] Drawing 2 is what showed the example of important section composition of the optical displacement meter 1 of this invention indicated to claim 2 gives the same numerals to the conventional optical displacement meter 100 and identical parts which were mentioned above and omits explanation. In a figure 10 is a level discrimination section with the comparator 10A which outputs a discrimination signal when the summed signal outputted from the adder circuit 113 exceeds the maximum level EH and the comparator 10B which outputs a discrimination signal when a summed signal falls from minimum level EL.

[0018] The resistance R1 which connects the variable amplifier 12 (13) to the amplifying circuit 12a (13a) R2 R3 ... It has come to be able to carry out the switch setting of the amplification factor discretely by carrying out the one drive of FET (F1 F2 F3 ... Fn) by which Rn was respectively connected to series selectively.

[0019] When 11 is an amplification factor control section with the rotary switch 11a shown equivalent and a clock signal is inputted If the discrimination signal is outputted from the comparator 10A exceeding the maximum level EH a summed signal The control signal for reducing the amplification factor which switches the rotary switch 11a and is set up now by one step is simultaneously sent out to the variable amplifiers 12 and 13 On the contrary if a summed signal falls from minimum level EL and the discrimination signal is outputted from the comparator 10B If the control signal to which the amplification factor set up now is made to increase by one step is simultaneously sent out to the variable amplifiers 12 and 13 and minimum level EL and the maximum level EH do [ a summed signal ] and the discrimination signal is not outputted from the level discrimination section 10 Operation which makes the amplification factor set up now without switching the rotary switch 11a hold as it is is performed.

[0020] Thus since the summed signal outputted from the adder circuit 113 by the two comparators 10A and 10B of the level discrimination section 10 is supervising entering between the maximum level EH and minimum level EL

according to the optical displacement meter 1 of this inventionThe number of the comparators to be used is also two sufficientwithout requiring the accuracy of a comparatorsince the range of the voltage which does not need to form many comparators like before and is compared is being fixed.

[0021]Drawing 3 is what showed the entire configuration figure of the optical displacement meter 1 shown in drawing 2attaches the numerals same about the portion and identical parts which were shown in the conventional displacement gage 100 and the above-mentioned example of important section compositionand omits explanation.

[0022]In the above-mentioned optical displacement meter 1drawing 4 is what showed the detailed example of composition at the time of setting the variable set number of the amplification factor of the variable amplifiers 12 and 13 to 2attaches the numerals same about the portion and identical parts which were shown in the conventional displacement gage 100 and the above-mentioned example of important section compositionand omits explanation.

[0023]The level discrimination section 10 comprises the comparators 10A and 10B and the resistance R10-R12.

If the summed signal outputted from the adder circuit 113 exceeds the maximum level EHIf the output level of the comparator 10A is set to "L" and a summed signal falls from minimum level EL converselyThe output level of the comparator 10B is set to "L"and when a summed signal is larger than minimum level EL and smaller than the maximum level EHthe signal of the "H" level is outputted from the both sides of the comparators 10A and 10B.

[0024]The amplification factor control section 11 comprises NOT circuits 11a and 11bNAND circuits 11c and 11dRS flip flop 11eand 11 f of D flip-flops. In this amplification factor control section 11as shown in (a) - (g) of drawing 5when 11 f of D flip-flops are reset (Q bar output is "H")FET (F1) of the variable amplifier 12 (13) flowsand the amplification factor is reduced.

In this stateeven if the discrimination signal of the "L" level is outputted from the

comparator 10A of the level discrimination section 10 exceeding the maximum level EH a summed signal It is prevented by NAND circuit 11 and a signal is not transmitted to the D-flip-flop 11f side but the amplification factor of the variable amplifier 12 (13) is reduced.

However if a summed signal falls from minimum level EL and the discrimination signal of the "L" level is outputted from the comparator 10B The signal of the "H" level is inputted into 11 f of D flip-flops through NOT circuit 11b 11 d of NAND circuits and RS flip flop 11e If a clock signal is inputted from the oscillating circuit 101 in this state 11 f of D flip-flops will be set (Q output is "H") FET (F1') of the variable amplifier 12 (13) flows and an amplification factor is increased.

[0025] It is an amplification factor changeover section when setting out of an amplification factor is automatically performed by the control mentioned above when the change-over switch 14a was switched to the point of contact a and it switches to the point of contact b it is fixed in the state where an amplification factor is high and conversely when 14 is switched to the point of contact c it is fixed in the state where an amplification factor is low.

[0026] Next although the operation of (a) - (c) of drawing 6 until it is what had and showed the position detection method of the optical displacement meter of this invention according to claim 3 for the time chart it outputs modulated light towards an object from a light emitting device and it receives the catoptric light by an object by a position detecting element is the same as that of the conventional displacement gauge In this invention method each of the position signal of the couple outputted from a position detecting element In [ amplify with the amplification factor selected from two or more amplification factors set up discretely beforehand search for an error integration signal comparing the summed signal of the position signal of the amplified couple with predetermined reference level and ] the input timing of a clock signal If this error integration signal is over the predetermined maximum level EH will make the amplification factor of the position signal of a couple increase from the present amplification factor by one step and conversely if this error integration signal is falling from

predetermined minimum level EL. Negative feedback control is made to be performed so that the amplification factor of the position signal of a couple may be reduced by one step from the present amplification factor. For this reason, since the error integration signal of the position signal of a couple enters in the window level which always becomes settled in a maximum level and a minimum level, a summed signal can be conjointly stabilized with optical feedback loop control, the breadth of a dynamic range can be stopped, and the arithmetic precision for the amount calculation of displacement can be raised.

[0027] Drawing 7 is what showed the example of important section composition of the optical displacement meter 2 of this invention indicated to claim 4. It gives the same numerals to the conventional optical displacement meter 100 and identical parts which were mentioned above and omits explanation. In a figure 20 is an error integration circuit which integrates with the error component as compared with reference level ER which was able to define beforehand the summed signal outputted from the adder circuit 113.

The acquired error integration signal is making the optical feedback loop form so that it may be transmitted to the modulation circuit (un-illustrating) side and the level of a summed signal may be stabilized in a predetermined value while being added to the level discrimination circuit 21 mentioned later.

21 is a level discrimination section with the comparator 21A which outputs a discrimination signal when the error integration signal outputted from an error integration circuit exceeds the maximum level EH and the comparator 21B which outputs a discrimination signal when an error integration signal falls from minimum level EL. The resistance R1 which connects the variable amplifier 23 (24) to the amplifying circuit 23a (24a) R2 R3 ... It has come to be able to carry out the switch setting of the amplification factor discretely by carrying out the one drive of FET (F1 F2 F3 ... Fn) by which Rn was respectively connected to series selectively.

[0028] When 22 is an amplification factor control section with the rotary switch 22a shown equivalent and a clock signal is inputted. If the discrimination signal is

outputted from the comparator 21A exceeding the maximum level EH an error integration signal. The control signal to which the amplification factor which switches the rotary switch 22a and is set up now is made to increase by one step is simultaneously sent out to the variable amplifiers 23 and 24. On the contrary, if an error integration signal falls from minimum level EL and the discrimination signal is outputted from the comparator 21B, send out simultaneously the control signal which reduces the amplification factor set up now by one step to the variable amplifiers 23 and 24. But, if an error integration signal is between minimum level EL and the maximum level EH and the discrimination signal is not outputted from the level discrimination section 21, operation which makes the amplification factor set up now without switching the rotary switch 22a hold as it is is performed.

[0029] Thus, like [ according to the optical displacement meter 2 of this invention ] the optical displacement meter 1 mentioned above with the two comparators 21A and 21B of the level discrimination section 21. Since the error integration signal outputted from the error integration circuit 20 is supervising entering between the maximum level EH and minimum level EL, the number of the comparators to be used is also two, sufficient without requiring the accuracy of a comparators since the dynamic range of the voltage which does not need to form many comparators and is compared is being fixed.

[0030] Drawing 8 is what showed the entire configuration figure of the optical displacement meter 2 shown in drawing 7, attaches the numerals same about the portion and identical parts which were shown in the conventional displacement gage 100 and the above-mentioned example of important section composition and omits explanation.

[0031] In the above-mentioned optical displacement meter 2, drawing 9 is what showed the detailed example of composition at the time of setting the variable set number of the amplification factor of the variable amplifiers 23 and 24 to 2, attaches the numerals same about the portion and identical parts which were shown in the conventional displacement gage 100 and the above-mentioned

example of important section composition and omits explanation.

[0032]The level discrimination section 21 comprises the comparators 21A and 21B, the resistances R20, R21 and R22.

If the error integration signal outputted from the error integration circuit 20 exceeds the maximum level EH, if the output level of the comparator 21A is set to "L" and an error integration signal falls from minimum level EL, conversely, the output level of the comparator 21B is set to "L", and when an error integration signal is larger than minimum level EL and smaller than the maximum level EH, the signal of the "H" level is outputted from the both sides of the comparators 21A and 21B.

[0033]The amplification factor control section 22 comprises NOT circuits 22a and 22b, NAND circuits 22c and 22d, RS flip flop 22e and 22f of D flip-flops.

About the operations, since it is the same as that of the amplification factor control section 11 of the displacement gage 1 mentioned above, explanation is omitted.

[0034]In this displacement gage 2, are making it reversed and connection of the comparators 21A and 21B of the level discrimination section 21 and NOT circuits 22a and 22b of the amplification factor control section 22 by this. If an error integration signal increases, an amplification factor will be made to increase, and if an error integration signal falls, it is made to make the negative feedback control which reduces an amplification factor performed conversely.

[0035]NOT circuit 26, FET 27 and the voltage follower circuit 28 which were connected to the oscillating circuit 101. Only the period when the oscillation pulse is outputted is controlling so that the error integration signal outputted from the error integration circuit 20 is transmitted to the modulation circuit 102 side and feedback control is performed.

[0036]Like the amplification factor changeover section 14 mentioned above, if the change-over switch 25a is connected to the point of contact a, the amplification factor changeover section 25. The change of an amplification factor is



automatically performed by the control mentioned above and when it connects with the point of contact bit is fixed in the state where an amplification factor is high and conversely when it connects with the point of contact cit is fixed in the state where an amplification factor is low.

[0037]

[Effect of the Invention] Since control is automatically performed so that it may always enter in a predetermined window level according to the position detection method of this invention according to claim 1 the summed signal of the position signal of the couple outputted from a position detecting element so that it may be understood from the above explanation it can become possible to press down the dynamic range of a summed signal and the arithmetic precision for calculation of the amount of displacement can be raised. According to the optical displacement meter of this invention according to claim 2 the easy composition which uses two general-purpose comparators enables it to perform highly precise displacement measurement processing by using the method according to claim 1. According to the position detection method of this invention according to claim 3 an error integration signal is searched for comparing with reference level the summed signal of the position signal of the couple outputted from a position detecting element Since control is automatically performed so that the error integration signal searched for may always enter in a predetermined window level it can become possible to press down the dynamic range of a summed signal conjointly with the optical feedback loop and the arithmetic precision for calculation of the amount of displacement can be raised. According to the optical displacement meter of this invention according to claim 4 the easy composition which uses two general-purpose comparators enables it to perform highly precise displacement measurement processing by using the method according to claim 3.

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## DESCRIPTION OF DRAWINGS

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[Brief Description of the Drawings]

[Drawing 1](a) - (c) is a time chart explaining this invention method according to claim 1.

[Drawing 2]It is an example figure of important section composition of the optical displacement meter of this invention according to claim 2.

[Drawing 3]It is a detailed example figure of composition of the optical displacement meter of this invention according to claim 2.

[Drawing 4]In the optical displacement meter shown in drawing 3it is a detailed example figure of composition in case the amplification factor of a variable amplifier is two steps.

[Drawing 5](a) - (g) is a time chart explaining operation of the amplification factor control section of the optical displacement meter shown in drawing 4.

[Drawing 6](a) - (c) is a time chart explaining this invention method according to claim 3.

[Drawing 7]It is an example figure of important section composition of the optical displacement meter of this invention according to claim 4.

[Drawing 8]It is a detailed example figure of composition of the optical displacement meter of this invention according to claim 4.

[Drawing 9]In the optical displacement meter shown in drawing 7it is a detailed example figure of composition in case the amplification factor of a variable amplifier is two steps.

[Drawing 10]It is an example figure of composition of the conventional optical displacement meter.

[Drawing 11]It is an explanatory view of the variable amplifier of operation.

[Drawing 12](a) - (c) is a time chart explaining operation of the optical displacement meter shown in drawing 10.

[Description of Notations]

104 ... Light emitting device (laser diode)

105 ... Position detecting element

12 ... Optical displacement meter

12132324 ... Variable amplifier

113 ... Adder circuit

1021 ... Level discrimination section

1122 ... Amplification factor control section

ER ... Reference level

20 ... Error integration circuit

EH ... Maximum level

EL ... Minimum level

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